

CBR based Performance Evaluation on FSR, DSR, STAR-LORA, DYMO Routing Protocols in MANET

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Abstract—For last one decade lot of researchers were conducted extensive work on performance evaluation among routing for tremendous rise in technological advancement. In these protocols, Routing process is a tedious job due to changing its topology over time. Since Mobile ad hoc network is a set of independent nodes move freely throughout network, to which all of them are created for the purpose of data transfer with limited battery backup. We need efficient routing protocol is needed to guide signals from source to destination through number of hops within time and several routing strategies has been proposed in last decade for ad-hoc network. In this paper, we leave efficient routing strategy to public to determine and extract efficiency from thoroughly perform simulations and comparative analysis of specified proactive type routing protocols and specified reactive type routing protocols with few nodes using Qual-Net Simulator and summarizes the results.

Keywords— DSR, DYMO, STAR-LORA, FSR, Routing Strategies

I. INTRODUCTION

In past ten years, several researchers have conducted comparative study and performance evaluation[1][2][3] among several routing protocols with respect to performance metrics over nodes ranges from 50 to 200 were deployed in MANET. In the twenty first century there have been a lot of articles are published regarding routing protocols in the field of wireless mobile ad hoc networks using ns2 simulator and Qualnet simulator 5.0.2. But there is missing in practicality in real world and really useful for public. In this paper we leave efficient routing strategy to public from obtaining results through[18] comparative study between proactive type Fisheye State Routing Protocol (FSR), proactive type Source Tree Adaptive Routing protocol (STAR) and Reactive type Dynamic Source Routing (DSR) and Reactive type Dynamic MANET On demand Routing Protocol (DYMO) are analyzed and presented and left to implementers whatever ease of routing technology is available in which how packets are delivered without Access Point. With this paper to explore the impact of QoS[22] metrics such as throughput, average end to end delay and average jitter on routing between nodes where we applied under Constant Bit Rate (CBR) client server traffic conditions using QualNet 5.0.2 simulator[13]. To show the performance efficiency in terms of plotting graphs represents that X axis indicates Node Count starting from 2 nodes to 12 nodes and Y axis indicates the Quality of Service metric by using simulator only. The rest of this paper is organized as follows.

In section 2 brief introductions to various routing strategies and its literature survey has been presented. Section 3 briefly explores test scenarios between STAR, FSR and DSR, DYMO routing protocol using QualNet 5.0.2 network simulator for 2, 4, 8, 10, 12 stationary nodes. In section 3 related works about test cases is presented. Simulation environment and simulation setup used in the work and running a scenario is discussed in section 4. In section 5 the results of the performance evaluation are thoroughly discussed. Conclusion & Future work is given in section 6.

II. LITERATURE SURVEY

Routing protocol in MANET is the prototype in which determination of selecting path by initiation of each node (especially source node) to route packets to concerned destination over wireless media based CBR traffic. This work focuses on efficiency of routing protocol among protocols for better construction of mobile ad-hoc networks. Each node[2] participates in an ad hoc routing protocol that allows it to discover “multi-hop” paths through the network to any other node. Some researchers proposed another article about routing is concerned with in electronic data networks which uses packet switching technology[3]. The fundamental principle of a routing protocol is to deliver the packets from source to destination with enhanced performance in terms of minimization of delay. Routing protocols are generally necessary for maintaining effective communication between distinct nodes. Routing protocol not only discovers network topology but also built the route for forwarding data packets and dynamically maintains routes between any pair of communicating nodes. Routing protocols are designed to adapt frequent updates in the network due to mobility nature in MANET. Traditionally, MANET Routing protocol strategies classified into two ways as shown in fig. 1

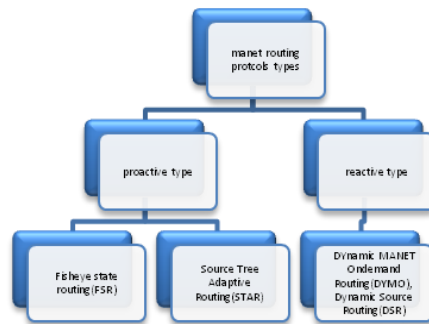


Figure 1 Classification of MANET routing protocols

2.1 Proactive Routing Strategy

Proactive Routing Strategy also called table driven, or data gram approach in packet switching network. It maintains routing table using the routing information learnt from neighbours on periodic basis. Main characteristics of these protocols include: distributed, shortest-path protocols, maintain routes between every host pair at all times, based on periodic updates of routing table and high routing overhead and consumes more bandwidth[4]. We are discuss comparative analysis between the following strategies in detail. Now we discuss the following kinds in this strategy.

1. Fisheye State Routing (FSR) [6]
2. Source Tree Adaptive Routing (STAR) [10]

2.1.1 Fisheye State Routing (FSR)

The FSR protocol[6] is the next generation technology of Global State Routing strategy(GSR). FSR maintains Entries of nearby nodes in the routing table are updated and exchanged with neighbours more frequently (to reduce the update message size).The accuracy of route increases as packets gets closer to the destination. The main drawback of FSR is as the mobility of remote nodes increases the accuracy of the routing information decreases.

2.1.2 Source -Tree Adaptive Routing (STAR)

The STAR protocol [10][11] is also called STAR – LORA(Least Overhead Routing Adaptive) based on the link state algorithm. Each router maintains a source tree, which is a set of links form a graph (V,E) containing the preferred paths to destinations. This protocol has significantly reduced the amount of routing overhead disseminated into the network by using a least overhead routing approach (LORA), to exchange routing information. It also support optimum routing approach (ORA) if required. This approach eliminated the periodic updating procedure present in the Link State algorithm by making update dissemination conditional. Each node keeps the state of subset of the links, i.e., the links of the source trees of other nodes and all of its links.The source tree of a node is the tree composed of all links that constitute the preferred routes to all destinations. STAR based on the trees reported by neighbours and the state of its links, each node builds a partial topology graph that is used to build the routing table. STAR is a scalable algorithm.

2.2 Reactive Routing Strategy

Reactive Routing strategy[4] are also called demand driven approach or virtual circuit approach in packet switching network. that find path as and when required. They maintain information about the active routes only. They performs route discovery phase before data transmission by flooding route request packet and destination node reply with route reply packet. A separate route maintenance procedure is required in case of route failure. Main Characteristics of these routing protocols are: determine routes as and when required, less routing overhead, source initiated route discovery and more route discovery delay. The following are used for this kind.

1. Dynamic MANET On-Demand Routing (DYMO) [7]
2. Dynamic Source Routing (DSR) [9]

2.2.1 Dynamic MANET On-Demand Routing (DYMO)

Dynamic MANET On-demand (DYMO)[7] routing protocol is a source initiated or reactive routing strategy in which multihop routing is built up between participating nodes that wish to communicate. The basic operations of the DYMO protocol are route discovery and route maintenance. During route discovery the originating node initiates dissemination of a Route Request (RREQ) throughout the network to find the target node. During this dissemination process, each intermediate node records a route to the originating node. When the target node receives the RREQ, it responds with a Route Reply (RREP) unicast toward the originating node. Each node that receives the RREP records a route to the target node, and then the RREP is unicast toward the originating node. When the originating node receives the RREP, routes have then been established between the originating node and the target node in both directions. During route maintenance, all nodes maintain their routes and monitor their links. When a packet is received for a route that is no longer available the source of the packet is notified. A Route Error (RERR) is sent to the packet source to indicate the current route is broken. Once the source receives the RERR, it re-initiates route discovery if it still has packets to deliver.

2.2.2 Dynamic Source Routing (DSR)

DSR is an on demand routing protocol in which a sender determines the exact sequence of nodes through which a packet is propagated. The packet header contains a list of intermediate nodes for routing. Route cache is maintained by each

node which caches the source route that it has learned. The major components of DSR are “Route Discovery” and “Route Maintenance” which work together for determining and maintaining routes to arbitrary destinations [5]. It is designed to restrict the bandwidth consumed by control packets in ad hoc wireless networks by eliminating the periodic table-update messages required in the table-driven approach. A route is established by flooding Route Request packets in the network. [8].

III. RELATED WORK

In this paper, we have taken two different scenarios[19]. In the first scenario, traffic pattern is taken as CBR Client and no. of nodes have been varied and performance comparisons have been made between STAR-LORA,FSR and DYMO,DSR protocol. In the second scenario, traffic pattern is taken as CBR Server have been varied and performance comparisons have been made between STAR-LORA,FSR and DYMO,DSR protocols.. The QoS can be defined as the manner that the service of delivery of packages is supplied and who can be characterized by various parameters of performance like, the throughput, the delay variation (jitter).

3.1 Test Scenario 1

In first scenario we have taken CBR Client as traffic pattern. Parameters are specified in table 1

Table 1: Parameters for Scenario 1

Parameter	value
Terrain size	1500 X 1500
Number of nodes	2,4,6,8,12
Traffic type	Constant Bit Rate client
Packet size	512
Mobility	Random way
Speed	100 mps
Pause time	15,20,25
Simulation time	3000 sec
Routing protocol	FSR,STAR-LORA,DYMO,DSR

3.2 Test Scenario 2

In first scenario we have taken CBR Server as traffic pattern. Parameters are specified in table 2

Table 2: Parameters for Scenario 2

Parameter	value
Terrain size	500 X 500
Number of nodes	2,4,6,8,12
Traffic type	Constant Bit Rate Server
Packet size	512
Mobility	Random way
Speed	100 mps
Pause time	15,20,25
Simulation time	300sec, 3000 sec
Routing protocol	FSR,STAR- LORA,DYMO,DSR

IV. SIMULATION ENVIRONMENT

The Qualnet 5.0.2 simulator is used for the design of scenarios in graphical environment. To[15] give an idea of how (in terms of quantitative) the scenario performs it can be run using the QualNet Animator. Figure 2 shows the Animator with the previously designed scenario in action. On the right side you can enable or disable various types of animations. In the Layers tab animations for each of the 7 OSI layers can be enabled or disabled individually.

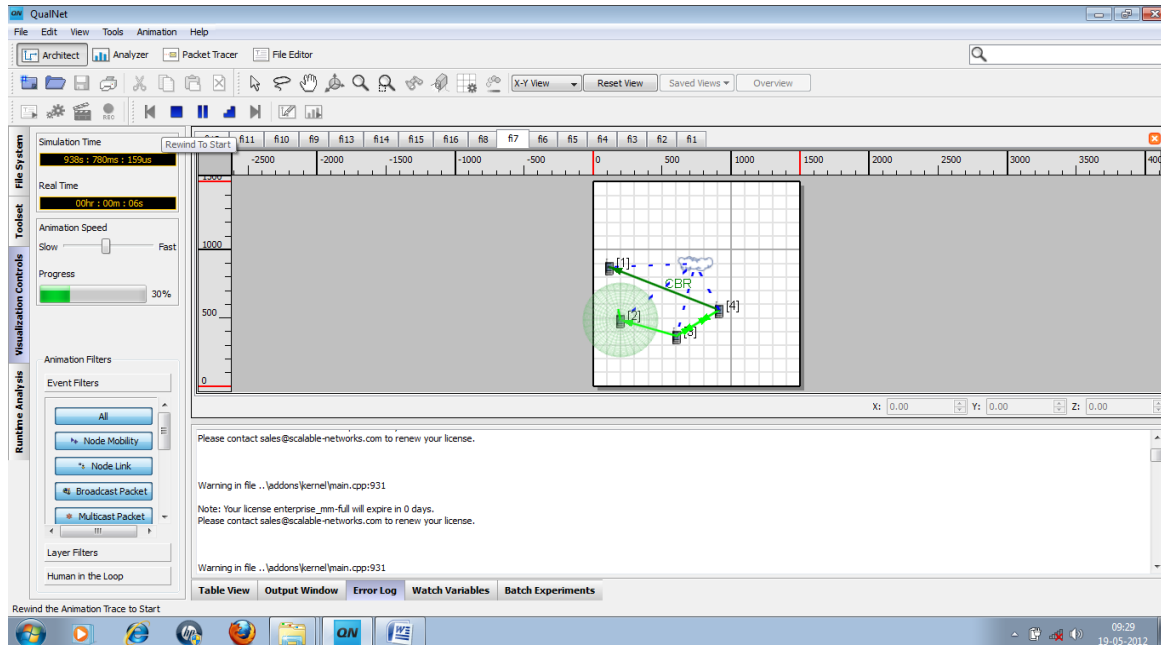


Figure 2 : Snap shot of QualNet5.0.2 Animator in Action

4.1 Experimental Setup

The study has been done to place require number of nodes changes dynamically on canvass plane as shown in Fig 3 and compare the efficiency of four different routing protocols, two of them are from proactive type and rest of them are reactive type in Mobile Ad hoc Networks. The tool used is QualNet5.0.2, the Quality of Service parameters are Throughput, Average End to End Delay and Average Jitter. The simulation using 2,4,6,8 and 12 nodes. The performance of all four routing protocols is carried out and results are compiled.

4.2 Performance Metrics

Now we are conducted extensive calculation on metrics based on terrain size. Hence terrain size varies, the corresponding metrics are rapidly changes while number of nodes are fixed. Here we perform rigorous experimental scenarios are deployed in QualNet simulator to generate graphs with suitable metrics. The following metrics are studied and applied to current scenarios as shown in table 3,4 and 5.

4.2.1 Average End To End Delay

It is the average time it takes a signal travel from process at source node service access point(SAP) to process at destination node service access point(done at SAP of transportation layer in TCP/IP protocol suite). This metric is calculated by subtracting time at which first packet was transmitted by source from time at which first data packet arrived to destination. This metric is significant in understanding the delay introduced by path discovery.

4.2.2 Throughput

The throughput of the protocols can be defined as total number of signalling elements travelled at a unit time. It is the amount of data per time unit that is delivered from one node to another via a communication link. The throughput is measured in bits per second (bit/s or bps).

4.2.3 Average Jitter

Average Jitter[21] is the variation of the packet arrival time. In jitter calculation the variation in the packet arrival time is expected to be low. The delays between the different packets need to be low for better performance in ad-hoc networks. It becomes a matter of concern if it is more than the threshold value, which is different for data, voice or video transmission services.

4.3 Results & Comparisons

Table . 3 CBR client Througput (Bits/sec)

nodes #	FSR	STAR-LORA	DYMO	DSR
2	4274	4274	4274	8520
4	4274	4274	4274	8520
6	4274	4274	4274	8520
8	4274	4274	4274	8520
12	4274	4274	4274	8520

Table. 4 CBR Server Average End to End delay (s)

Nodes #	FSR	STAR-LORA	DYMO	DSR
2	0.003721	0.004988	0.001978	0.026
4	0.003734	0.004988	0.018556	0.026
6	0.003756	0.004988	0.01964	0.139
8	0.003769	0.00698	0.018	0.139
12	0.003794	0.004789	0.02164	0.04587

Table. 5 CBR Server Average Jitter (s)

Nodes #	FSR	STAR-LORA	DYMO	DSR
2	0.0003288	0.00015867	0.0128654	0.0135689
4	0.0003287	0.00015869	0.0126261	0.032145
6	0.0003324	0.00015874	0.012964	0.015894
8	0.0003365	0.00015876	0.013	0.016154
12	0.0003381	0.00105865	0.013	0.016257

Note: The above results will be taken from analyzer screen in Qualnet and it is plotted with the help of Microsoft Excel 2007 tool. Figures 5,6, 7,8,9 and 10 shown figures 0,5,10,15 in X axis instead of display figures 2,4,6,8,10 and 12 nodes on X axis in Qualnet experimentation. Readers can understood these numbering notations.

4.4 Running A Scenario

QualNet 5.0.2 has a configuration window which contains several attributes of each node layer information. However we have to focus on network layer protocols such as DYMO, STAR,DSR and application layer protocol such as Fisheye routing protocol. To run each protocol[20][21] we are loading values of simulation time, number of seeds (here only one seed is used in simulator) and throughput, average end to end delay, average jitter, then apply run simulation and play it then automatically the present scenario is get animated. Ultimately we have been produce several graphs according metrics such as number of control packets on media, total packets sent, number of control packets transmitted, being transmitted through animation, control overhead with respect to Node ID as shown in Fig. 3 to Fig 8. These results are obtained from the following analyzer windows.

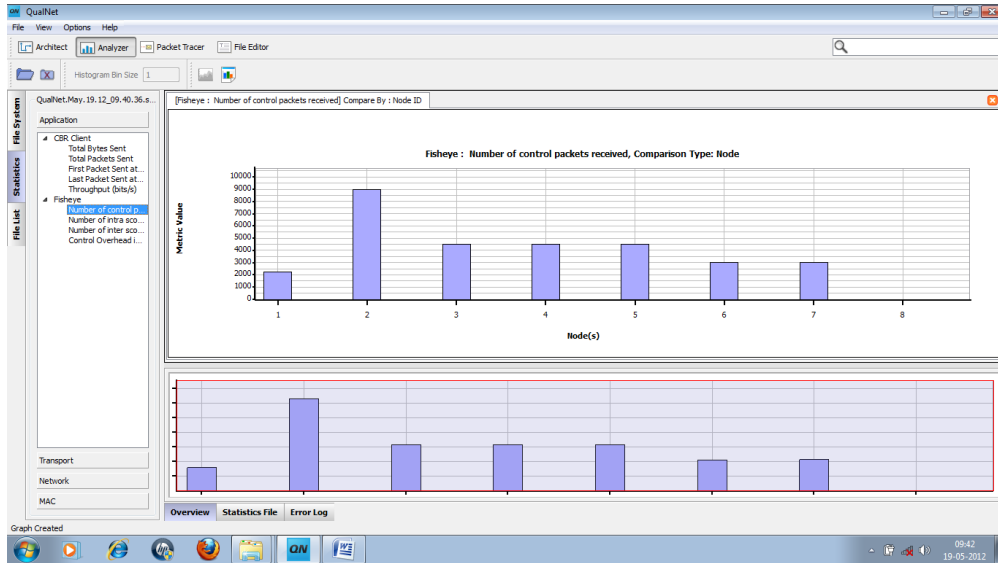


Figure 3 Number of control packets Vs node ID in Analyzer Window

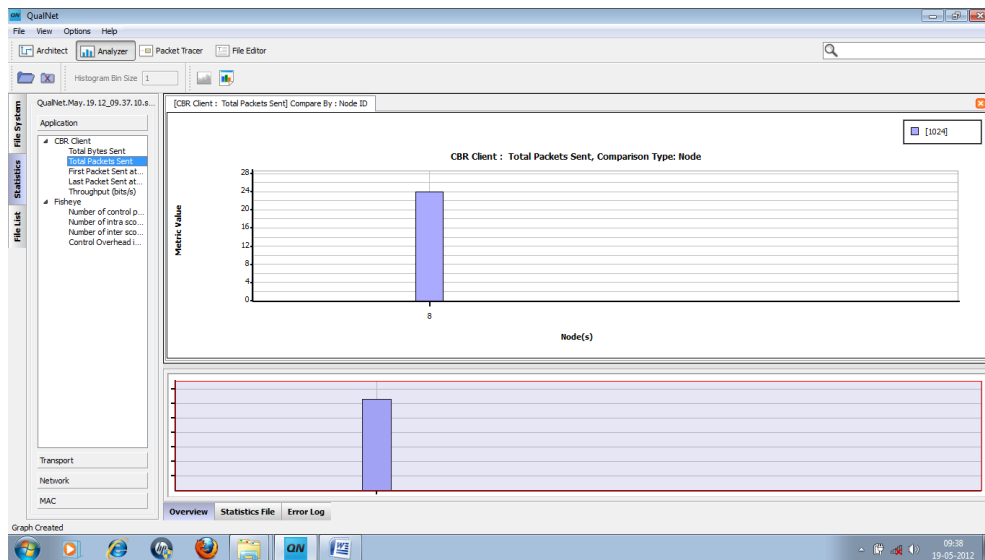


Figure 4 Total packet sent Vs node ID in Analyzer

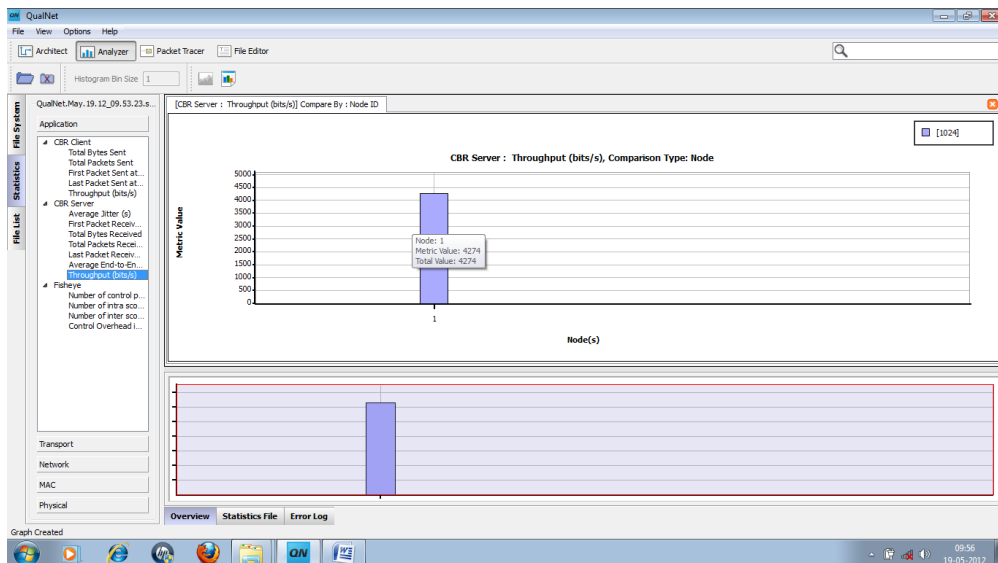


Figure 5 Throughput Vs node ID in Analyzer screen

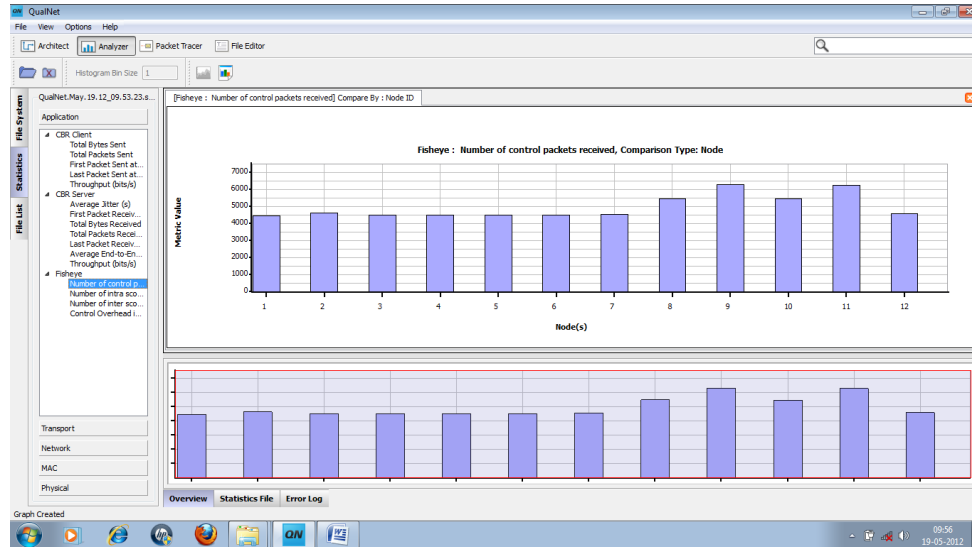


Figure 6 Fisheye Routing type No. of control packets transmitted Vs node ID in Analyzer Screen

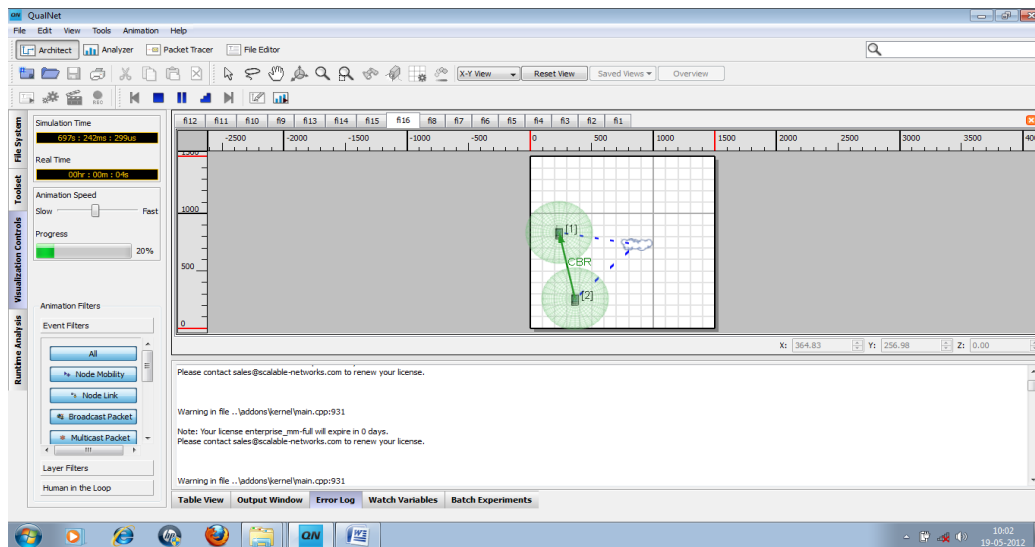


Figure 7 Two Nodes are being transmitted in Animation screen

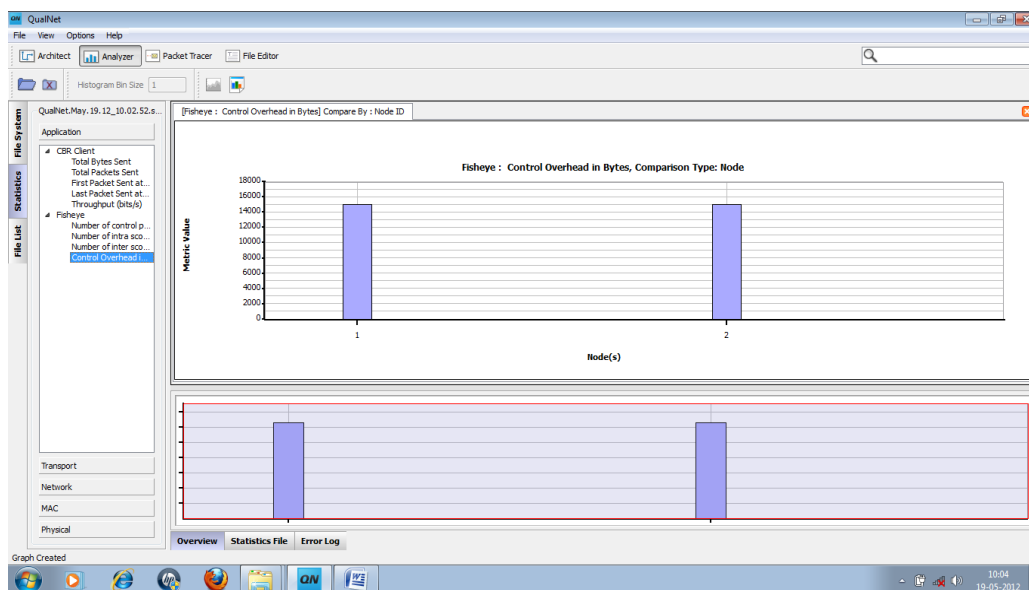


Figure 8. Control overhead Vs node ID in Analyzer screen

V. PERFORMANCE EVALUATION

The Qualnet 5.0.2 network simulator[14] has been used to analyze[16][17] the parametric performance of Source Tree Adaptive Routing Protocol (STAR), Fisheye State Routing Protocol (FSR), Dynamic Source Routing (DSR) and Dynamic MANET On demand Routing protocol (DYMO). The metric based evaluation is shown in Fig. 9 to Fig. 14.

5.1 Throughput

With the varying CBR data traffic the throughput is analyzed. The successful packet delivery at given nodes having number (ID) in an adhoc network is observed with increasing MAC based traffic load and mobility. It is found that DSR with least routing overhead uniformly performs better than FSR and STAR. The performance is shown in figure 9 and 10. Therefore FSR, STAR and DYMO has been plotted in first graph and DSR is plotted in second and next graph because DSR values are beyond the values of Previous graph. Similarly in next sections 5.2 and 5.3 assumed to put graphs separately.

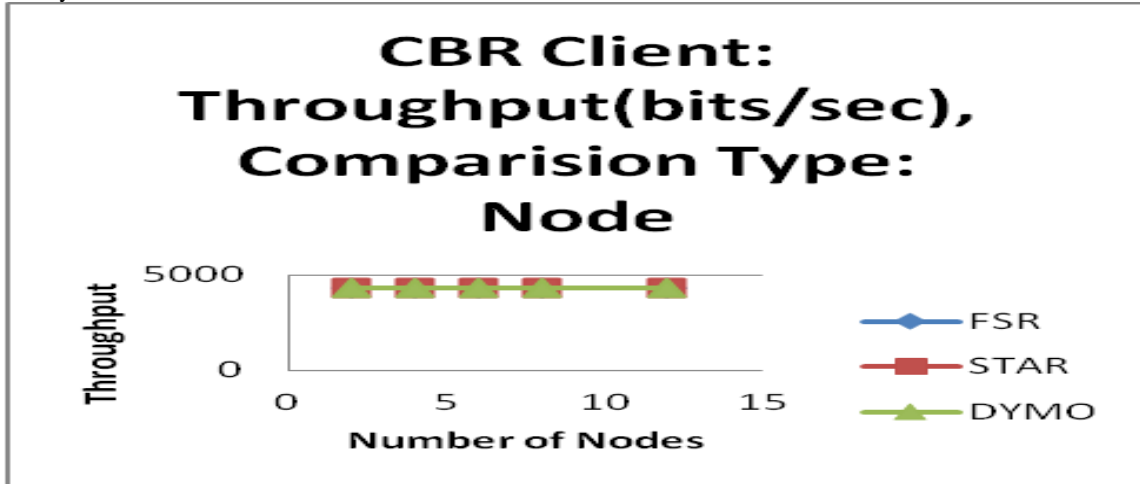


Figure 9 Graph for Throughput(Bits/sec) Vs nodes

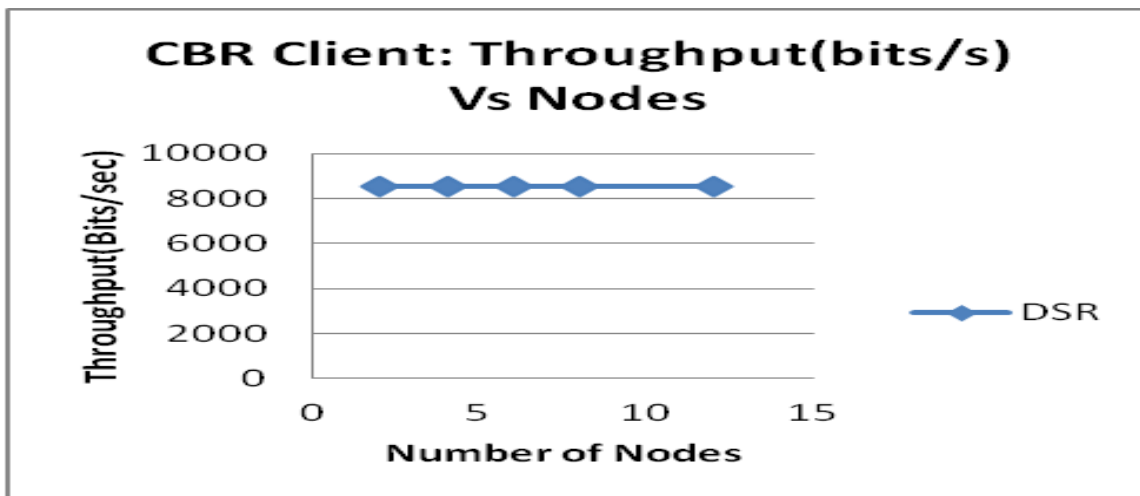


Figure 10 Graph for Average Throughput(Bits/s) Vs nodes

5.2 Average End-To-End Delay

It is a propagation time to deliver packet or signal from process (Application Programming Interface) at source to process at destination. To average up all times when data transfer phase is completed that process to process delivery time is called average end-to-end delay. Simply we call setup time+data transfer time+tear down time is referred to as delay of packet delivery. In this analysis it is observed as expected the delays are high in DSR in comparison to FSR and STAR. These delays are incurred by the FSR methods. The end-to-end delay is very less in case of FSR and STAR. Because FSR is a less over head to the packet within small geographical area. The performance is shown in fig. 11 and 12

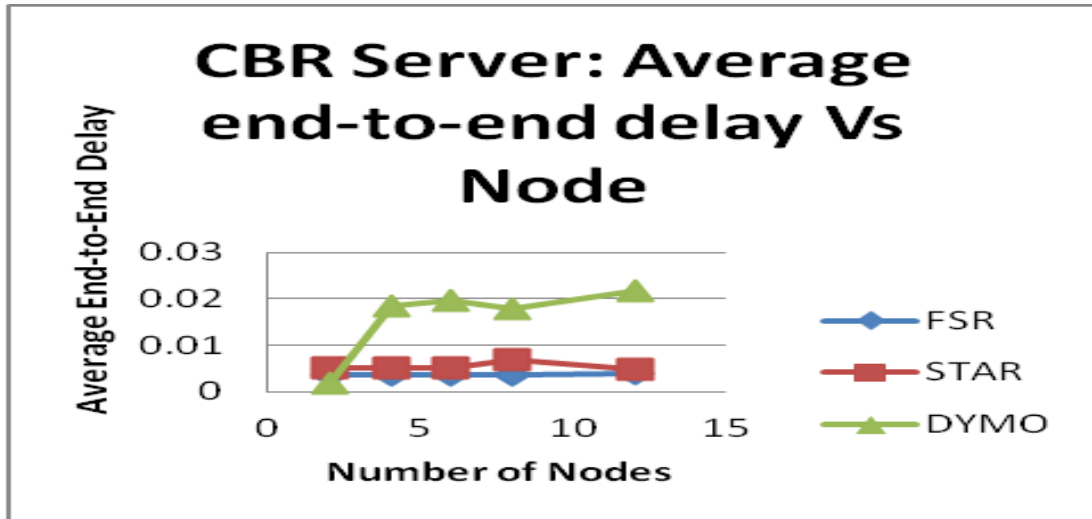


Figure 11 Graph for Average End-to-End delay Vs nodes

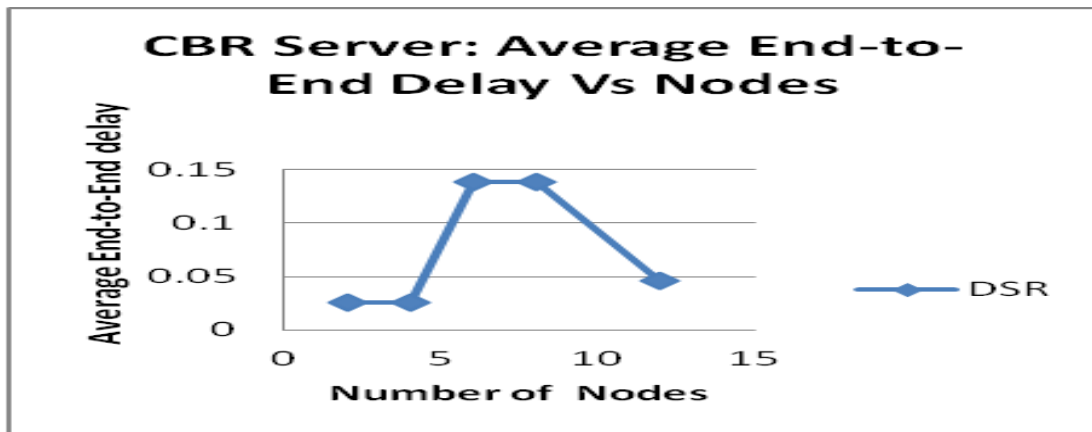


Figure 12 Graph for Average End-to-End delay Vs nodes

5.3 Average Jitter

Jitter, the variation of the packet arrival time, is an important metrics for any routing protocol. In this analysis it is found to vary. Initially it is low but for higher nodes ID than 12 it is high. The jitter for nodes 2,4,6,8 is high for both of the protocols due to larger distance between source and destination. In STAR it is due to limited no.of nodes as in FSR and DYMO, it is due to higher frequency of propagation. The jitter results are shown in fig. 13 and 14

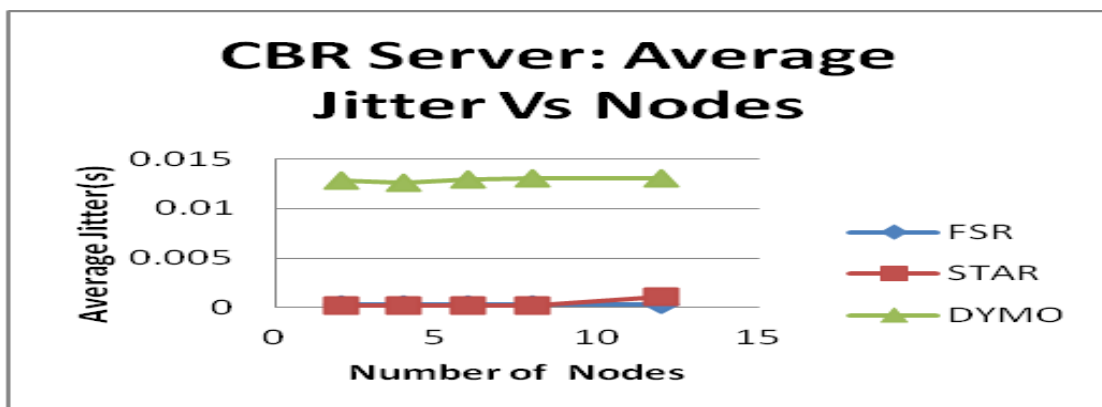


Fig. 13 Average Jitter (s) Vs nodes

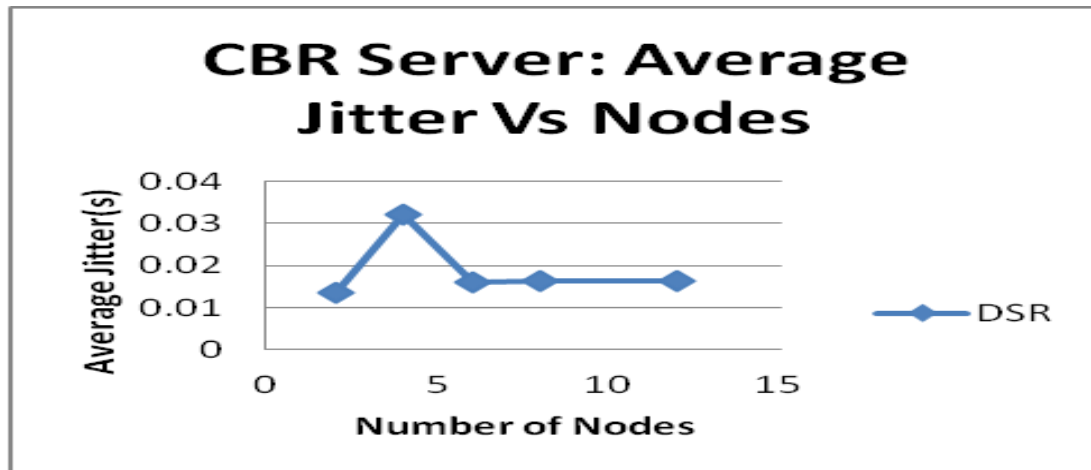


Fig. 14 Graph for Average Jitter Vs nodes

VI. CONCLUSION & FUTURE WORK

The performance evaluation of two proactive routing strategies (FSR, STAR) and two reactive routing strategies (DSR, DYMO) for stationary nodes are evaluated by varying the node density (2,4,6,8,12) using Qualnet 5.0.2 network simulator. From these graphs it can be realised that reactive routing protocol DSR only are suited for applications where average jitter and throughput are in danger situation and FSR are suited for Average end to end delay. The worst drawback [15] of the QualNet animator is its extreme high CPU utilization and its implementation in Java which makes it run very slowly on most machines. In this paper we leaves to researchers to enhance our mission to run scenarios not only these tools usage. However there is scope of examination over strategies for better tomorrow. One of our future research works is to develop an proposed algorithm on routing strategy can work in Bandwidth on demand working environment like banking sector, high secure communication, education system using high end tools.

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