e-ISSN: 2278-067X p-ISSN: 2278-800X



INTERNATIONAL JOURNAL OF ENGINEERING RESEARCH AND DEVELOPMENT

e-ISSN: 2278-067X p-ISSN: 2278-800X

CERTIFICATE

It is certified that the paper entitled by "Kinematic Modeling and Workspace Analysis of 4DOF Upper Limb Rehabilitation Robot" has been published in International Journal of Engineering Research and Development (IJERD).

Your article has been published with following details:

Author's Name: OLLOMO Dan Geoffrey

Journal Name: International Journal of Engineering Research and Development (IJERD)

Journal URL: www.ijerd.com

Journal Type: Online & Offline

Publication Year: 2025

Publication Month: November

Vol No.: 21

Issue No.: 11



Editor-In-Chief

International Journal of Engineering Research and Development (IJERD)

ISSN(Online): 2278-067X, ISSN(Print): 2278-800X

E-mail ID: ijerd@editormails.com

URL: www.ijerd.com

e-ISSN: 2278-067X p-ISSN: 2278-800X



INTERNATIONAL JOURNAL OF ENGINEERING RESEARCH AND DEVELOPMENT

e-ISSN: 2278-067X p-ISSN: 2278-800X

CERTIFICATE

It is certified that the paper entitled by "Kinematic Modeling and Workspace Analysis of 4DOF Upper Limb Rehabilitation Robot" has been published in International Journal of Engineering Research and Development (IJERD).

Your article has been published with following details:

Author's Name: XIANHUA Li

Journal Name: International Journal of Engineering Research and Development (IJERD)

Journal URL: www.ijerd.com

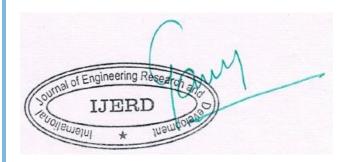
Journal Type: Online & Offline

Publication Year: 2025

Publication Month: November

Vol No. : 21

Issue No.: 11



Editor-In-Chief

International Journal of Engineering Research and Development (IJERD)

ISSN(Online): 2278-067X, ISSN(Print): 2278-800X

E-mail ID: ijerd@editormails.com

URL: www.ijerd.com