Night Patrolling Robot

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Abstract – This paper presents the implementation of a Night Patrolling Robot equipped with a monitoring and control algorithm. The Night Patrolling Robot operates on a Raspberry Pi platform and utilizes Internet of Things (IoT) technology. Serving as a crucial tool for national security, this robot is employed as a security solution across various organizations such as banks and hospitals. Comprising a Raspberry Pi, which acts as a compact single-board computer, a night vision camera, and a sound sensor, the Night Patrolling Robot system, also known as the spy robot system, is constructed. Users receive real-time information through the sound sensor's detection capabilities, facilitated by a web server, while the Pi camera simultaneously captures and transmits footage of moving objects to the server. Control room personnel can access the robot's data through a database created on the server. Furthermore, the robots can be programmed for autonomous movement using obstacle-detecting sensors to avoid collisions. This surveillance system, adaptable for deployment in various environments, including airports, retail centres, and businesses, offers customizable security solutions tailored to specific needs and settings.

Keywords-: Internet of Things, Virtual network Computing, Security, Database.

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I. INTRODUCTION

The realm of robotics is experiencing significant growth in today's society, with military organizations, businesses, academia, and research sectors emerging as primary users of well-established robotic technologies. Comparatively, the cost of designing and deploying a robot is notably lower than hiring a human caregiver. Additionally, reprogramming robots can be accomplished more efficiently, enabling swift adaptations to changing circumstances. These intelligent machines possess the capability to cover extensive areas and offer thorough monitoring, whether operating autonomously or under human supervision, even in unstructured environments.

In the realm of remote monitoring and control systems, such as consumer surveillance setups and smart home configurations, real-time object detection holds paramount importance, particularly in ensuring safety and security. Real-time human body detection serves a myriad of purposes across various applications, including communication, surveillance, and home security systems. In today's advanced landscape, criminal activities have evolved, with instances of theft and robbery occurring frequently. Deploying robots for nighttime patrols or in low-light conditions adds an extra layer of security to these systems. By operating in hazardous or remote areas, these robots mitigate risks to human security personnel. However, their optimal performance is achieved through synergy with human security guards, who can respond to events and make critical decisions based on the data provided by these robots.

Security is a vital aspect for any organization, encompassing sectors like hospitals, banks, etc., where manpower is predominantly utilized for security purposes. Recognizing the vulnerabilities associated with traditional security measures, such as keys and perimeter fencing, people and organizations are increasingly turning to technological solutions. Night patrolling robots offer a technologically advanced alternative, reducing the manpower required for security operations. In today's modern era, they enable the automation of security systems with minimal effort and tasks.

II. Literature Survey

1. A. K. Bandani (2023) [1] A. Bollampally, S. Sahithi, R. Naik, N. Kumar and Goutham designed and developed a spy robot with wireless night vision camera using Android. The primary goal of Design of spy Robot with wireless night vision camera using android is to create a robot that can monitor human activities. The robot goes around and collect audio-video data from the surrounding. The robot send data to distant IOT cloud database. By Transmitting commands via the Bluetooth software on our android phone we can direct the robot moments. The robottravels in the direction shown by the mobile device. We can watch camera footageon a PC.

2. D. Abhyankar (2021) [2] The Authors D. Abhyankar, G. Suresh, H. S. Karjule, P. Bhardwaj, H. Muleva and A. Mahajan focuses on developing a Night vision Bot using Dynamic IR and Object Detection,

various sensors. This robot has the ability that can be controlled from the distance. It uses the concept known as Dynamic IR to produce better

images. There is also an addition of object detection using machine learning Algorithm, there is an integration of IOT to control robot remotely.

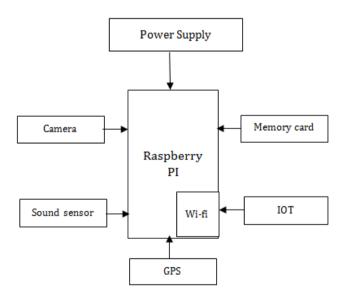
3. D. Sharma (2020) [3] The authors D. Sharma and U. Chauhan published war spying robot with wireless night vision camera, which published in paper 2020 in 2nd International Conference on Advances in Computing communication control and Networking. The main objective of this model is to deal with the security issues. Such as Terrorist activities. This is achieved by RF based spy robot. It consists of a wireless night vision camera which will record footages in dark and displayed it on our mobile screen. The project is more concerned and focused on Wi-Fi based communication.

4. J. N. Amrutha, K. R. Rekha(2020) [4] Night Vision Security Patrolling Robot Using Raspberry Pi was published at International Journal of Research in Engineering, Science and Management. This paper makes use of Raspberry pi to deal with monitoring system. Nowadays video surveillance is an important for security. High end camera is required to be used in various indoor and outdoor places. This paper

makes use of night vision camera to capture video during night time. It also uses PIR sensor and IR LED.It uses Wi-fi module and Sound sensor.

5. G. O. E. Abdalla (2017) [5] Implementation of spy robot for a surveillance system using Internet protocol of Raspberry pi was published on 2017 at 2nd IEEE International Conference on recent trends in Electronics, Information and Communication technology. It deals with the Monitoring and control algorithm through Internet of Things (IOT) has been developed which will save human live, reduces manual error and protect the country from enemies.

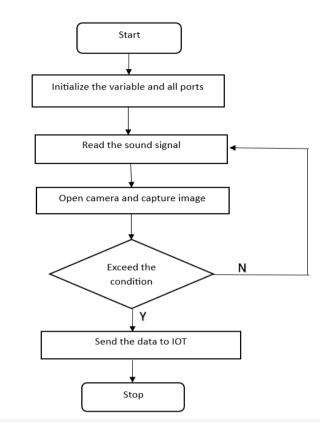
The robot comprises of Raspberry pi, Night vision camera and sensors. The live objects are detected by PIR sensor. The pi camera captures the moving objects which is posted inside webpage. The moment of robot is controlled automatically avoiding the collision. Such type of surveillance robot can be customized for various fields like banks, households etc.



III. Block Diagram:

The diagram illustrates a model featuring a Raspberry Pi equipped with a Wi-Fi module. This Raspberry Pi is linked to a night vision camera for nocturnal image capture, with the images being transmitted to a remote location for real-time monitoring. Additionally, the Raspberry Pi is connected to a sound sensor. The operational framework of the proposed system is elucidated as follows: upon detecting sound, the sound sensor triggers the camera to activate its shutter and capture images of the surroundings. These images are then transmitted to a locally hosted server, which includes a database for storing the images captured by the camera. Authorized personnel responsible for security can access these images from the database. The Night Patrolling Robot simplifies the task of security monitoring, enhancing overall surveillance capabilities.

Flowchart



IV. Methodology:

•Establishing Requirements: Comprehension the objective behind your nocturnal patrolling robot. Is it geared towards surveillance, security, or another purpose? Define the functionalities you envision for your robot, such as incorporating a camera for live streaming and infrared sensors for obstacledetection.

•**Procuring Components:** Acquire essential components including a Raspberry Pi (preferably Raspberry Pi 4 for enhanced performance), chassis, motors, and wheels for the robot's foundation. Obtain a motor driver board, like the L298N, to regulate the motors, and ensure a power source (battery pack) for both the Raspberry Pi and motors. Source sensors such as ultrasonic and infrared for navigation and obstacle detection, and consider optional additions like a camera module for live streaming and LED lights for nighttime visibility.

•Assembly: Construct the robot by following the manufacturer's instructions for assembling the chassis, motors, wheels, and motor driver. Establish connections from the motors to the motor driver board and then to the GPIO pins of the Raspberry Pi. Attach sensors, such as sound sensor, to the GPIO pins. If integrating a camera module, connect it to the Raspberry Pi's CSI (Camera Serial Interface) port.

• **Programming:** Develop the software to govern the robot's functionalities. Utilize Python, which is native to Raspberry Pi, for programming. Employ libraries like RPi.GPIO for motor control and sensor interfacing. Implement algorithms for navigation, obstacle avoidance, and planning patrol routes. If integrating a camera module, incorporate code for image capture or video streaming. Ensure the robot's capability to function autonomously, making decisions based on sensor input.

• **Robotics and Internet of Things:** Robotics and IOT are the two different fields where robotics deal with the advancement and development of robots which can be used in various fields such as security, education, healthcare. While IOT is a field where different physical devices can connect to each other. IOT platforms uses sensors that send and receive information through IOT platform. When robotics and IOT comes together it help us to create many new innovations. Which can be used in various businesses, military, corporate offices,

healthcare. Night Patrolling Robot uses combined robotics and IOT platform to work effectively and to perform its tasks efficiently.

• **Sound Localization:** Human ear has a tendency to identify, detect and analyse the noise and identify the direction of noise. Same tendency is provided tosound sensor. Sound sensor is used to identify the noise. A sensor which detects and measures physical devices and convert them into signals. The sound sensor is a module that monitors and detects the sound signals like voice, claps snaps, knocks, etc. night patrolling robot uses sound sensor, detect a sound of a person passing near by the robot. Irresponsive to the sound sensor, the shutter of camera gets open, which helps the robot to click the image of a cursor for the security purpose.

•Message Alert: Night Patrolling Robot is a revolutionary security solution that is changing the way we think about security. This paper covers the benefits of using a robot for night patrolling, its features, and how it can help improve safety and security in various settings. Message alert is a system which is used to notify person about the activities performed by robot. Night Patrolling Robot uses PI camera to click image of person and the robot send this image to the concerned person. To notify person about the image delivered to its system message alert system is used. When robot send image to system message is send to the person to alert him about the activity happening.

• **Testing and Calibration:** Thoroughly assess each component to validate its functionality. Calibrate sensors to ensure precise readings. Conduct testing of the robot's navigation and obstacle avoidance algorithms across diverse environments. Adjust code and hardware configurations as necessary.

•Deployment: Upon achieving satisfactory performance, deploy the robot for nocturnal patrolling in the designated area. Continuously monitor its operations and make any requisite updates or enhancements.

•Maintenance: Regularly inspect and uphold the robot to sustain its optimal performance. Replace batteries when depleted and clean sensors and camera lenses for sustained efficiency.

V. Components:

1. Raspberry Pi:

The most recent model in theRaspberry Pi computer world is the Raspberry Pi 4 Model B. Compared to the previous models, it shows revolutionary improvements in memory, networking, multimedia capabilities, and CPU speed. The Raspberry Pi 4 Model offers desktop performance on par with x86 entry-level PC systems.Raspberry PI 4 model B is been used in this model due to its more speed and memory than other Raspberry PI.

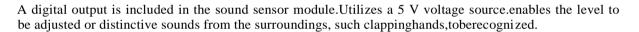


2. Pi Camera:

To enhance a video surveillance system's performance in low light, night vision camerasare employed. The essential characteristic that ties all of these cameras together is their infrared lighting, without which it is hard to even consider night time video surveillance.

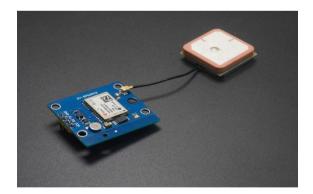


3. Sound Sensor:



4. GPS Module:

GPS stands for Global Positioning System. It is a satellitebased navigation system owned by the united states government. It provides critical positioning capabilities to military, civil and commercial users around the world.



VI. Result Analysis:

The evaluation of the night patrolling robot project reveals several significant findings. Initially, it confirms the effectiveness of the robot in conducting patrols during nighttime. Rigorous testing and observation demonstrate its ability to navigate various environments, effectively fulfilling its patrol duties. Moreover, the integration of advanced sensors and surveillance technology enhances the robot's capacity to autonomously detect and respond to potential security threats, thereby significantly strengthening the overall security infrastructure of the monitored area. Additionally, the project analysis highlights enhancements in operational efficiency and cost-effectiveness compared to traditional human patrolling methods. Automation of the patrol process reduces the need for human personnel to undertake repetitive and potentially hazardous nighttime patrols, thereby decreasing operational costs and minimizing risks to personnel safety, particularly in adverse weather conditions or high-risk situations. Furthermore, the data gathered during the project implementation

phase offer valuable insights for further refining and optimizing the robot's functionality. Monitoring and iterative improvements, guided by real-world performance data, are crucial for ensuring the long-term effectiveness and sustainability of the patrol robot system. Overall, the analysis underscores the successful deployment of autonomous surveillance technology in enhancing security measures. By leveraging cutting-edge robotics and artificial intelligence, the project showcases significant advancements in nighttime security operations, paving the way for future innovations in autonomous security systems.

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VII. Conclusion:

The IoT-based smart night patrolling robot represents a notable stride in surveillance and security technology. By amalgamating components like the Raspberry Pi, Pi camera module, sound sensor, motor driver, motors, and buzzer, a system has been crafted capable of autonomously patrolling designated areas while providing real-time feedback. Its web-based interface allows users remote monitoring and control, amplifying accessibility. This proposed system exhibits adaptability, primed for customization to meet diverse needs, rendering it a versatile solution for surveillance and security tasks. By potentially diminishing the need for manual labour in night patrolling, the system reduces the likelihood of human error, thereby enhancing operational efficiency and effectiveness. In essence, it signifies a substantial leap forward in the domain of night patrolling operations, promising augmented security and surveillance, cost efficiency, and operational efficacy. With its potential applicability across industrial sites, residential zones, and public areas, the system holds promise for bolstering safety and security on various fronts. This proposed system stands as a commendable addition to the realm of IoT-based robotics, furnishing a dependable and economical avenue for surveillance and security endeavours.

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