

Development of a MPPT-based Single Phase PWM Solar String Inverter for AC output for off grid applications

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Abstract: A microcontroller based technique of generating a sine wave from the solar panel output is designed and implemented in this paper using a two-stage topology for a solar string inverter. This paper presents the development of a maximum power point tracking (MPPT) and control circuit for a single phase inverter using a pulse width modulation (PWM) IC. The attractiveness of this configuration is the elimination of a complex circuitry to generate oscillation pulses for transistor switches. The controller IC TL494 is able to generate the necessary waveforms to control the frequency of inverter through proper use of switching pulse. The DC to AC inversion is successfully achieved alongside the switching signals; the circuit produced inverter output of frequency nearly 50 Hz. The main objective of the proposed technique is to design a low cost, low harmonics voltage source inverter essentially focused upon low power electronic appliances using variable solar power as inputs.

Keywords: AC solar panels, DC-AC converters, MPPT charge controllers, PWM inverters, solar string inverters.

I. INTRODUCTION

a) Maximum Power Point Tracking (MPPT)

When a solar PV module is used in a system, its operating point is decided by the load to which it is connected. Also, since solar radiation falling on a PV module varies throughout the day, the operating point of the module also changes throughout the day. Ideally under all operating conditions, one would like to transfer maximum power from a PV module to the load. In order to ensure the operation of PV modules for maximum power transfer, a special method called Maximum Power Point Tracking (MPPT) is employed in PV systems where, electronic circuitry is used to ensure that maximum amount of generated power is transferred to the load. The maximum power point tracking mechanism makes use of an algorithm and an electronic circuitry. The mechanism is based on the principle of impedance matching between load and PV module which is necessary for maximum power transfer. This impedance matching is done by using a DC to DC converter by changing the duty cycle (d) of the switch.

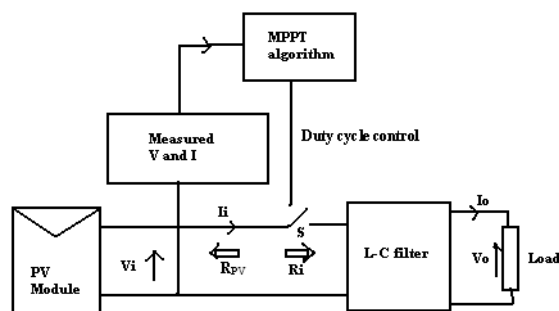


Fig.1 Block diagram of the MPPT algorithm along with the circuit.

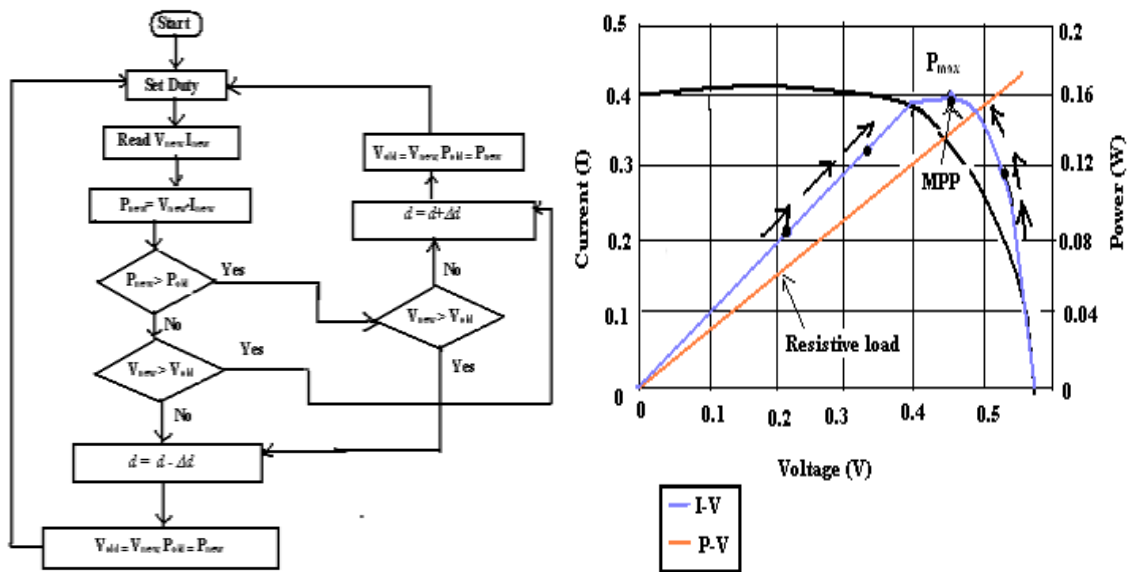


Fig.2 (a) Flow chart of hill climbing method and (b) schematic diagram demonstrating how the operating point moves towards the maximum power point(MPP)

The power from the solar module is calculated by measuring the voltage and the current. This power is an input to the algorithm, which then adjusts the duty cycle of the switch, resulting in the adjustment of reflected load impedance according to the power output of PV module. For instance, the relation between the input voltage (V_i) and the output voltage (V_o) and impedance of load (R_L) reflected at the input side (R_i) of a buck type DC to DC converter can be given as:

$$V_o = V_i \times d$$

$$R_i = \frac{R_L}{d^2}$$

Where d is the duty cycle. By adjusting the duty cycle, R_i can be varied which should be same as the impedance of solar PV module (R_{pv}) in a given operating condition for maximum power transfer [15,16].

b) Inverter: A power inverter, is an electrical power converter that changes direct current (DC) to alternating current (AC); the converted AC can be at any required voltage and frequency with the use of appropriate transformers, switching and control circuits. In an inverter, dc power from the PV array is inverted to ac power via a set of solid state switches—MOSFETs or IGBTs—that essentially flip the dc power back and forth, creating ac power. Fig.3 shows basic H-bridge operation in a single-phase inverter. This solid state switching process is known as inversion [6].

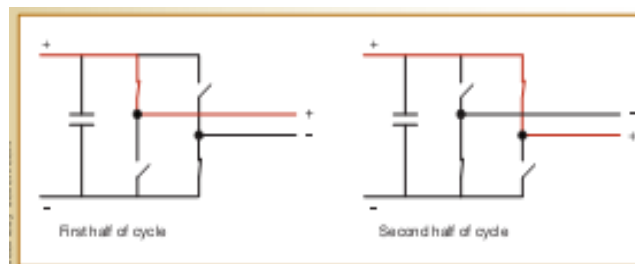


Fig.3 An H-bridge circuit performs the basic conversion from dc to ac power.

The inverter will receive input of 12 V dc from the controller circuit and it will convert this to 230 V ac. The inverter circuit designed as an H bridge inverter with an IC which incorporates PWM technique and converts, with the help of a 12V/230 V transformer, the obtained 12V dc from MPPT circuit, to the output 230V ac for use.

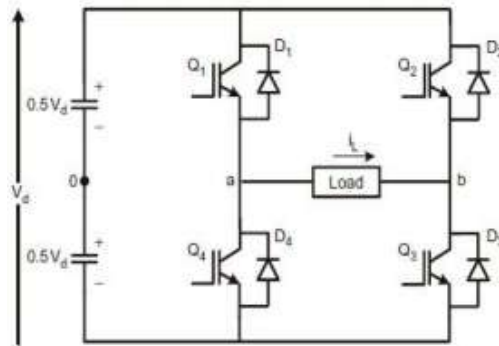


Fig. 4 Full bridge single phase inverter

The full bridge (single phase) inverter is built from two half bridges connected to form what is known as a full bridge or H-bridge inverter. Its arrangement is shown in figure 4. It comprises of DC voltage source, 4 power switches (usually bipolar junction transistors-BJTs, metal-oxide semiconductor field effect transistors-MOSFETs, insulated gate bipolar transistors- IGBTs or gate turned on transistors-GTOs) and the load.

To create a square-wave output voltage, the device pairs Q1Q3 and Q2Q4 are switched alternatively at a delay of 180 degrees. When Q1 and Q3 are ON with Q2Q4 OFF for a duration t, also with Q2Q4 ON and Q1Q3 OFF at t. Assuming there is a sinusoidal load current, the load will absorb power when Q1Q3 and Q2Q4 pairs are conducting alternatively whereas feed backing occurs when the diode pairs are conducting[22].

II. APPROACH AND METHOD

The block diagram for the circuit is as shown.

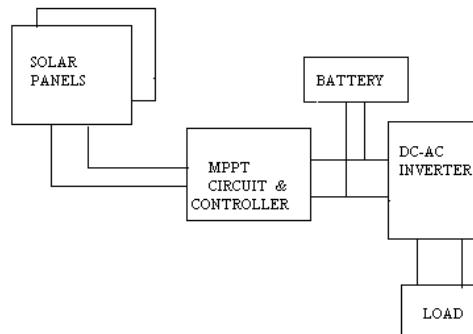


Fig.5 Block diagram for a solar power system

MPPT Circuit: The next step is to design and test the MPPT circuit. The voltage and the current output from the panel array have to be measured and the maximum power has to be supplied to the battery.

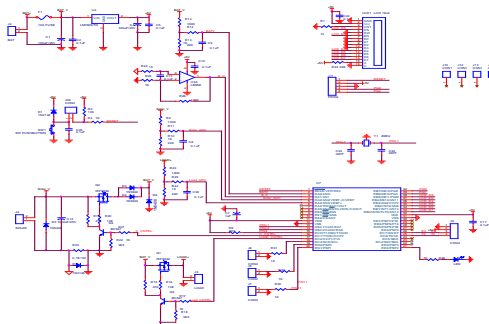


Fig.6 Schematic diagram for MPPT circuit



Fig.7 MPPT circuit.

Inverter Circuit: Next is the circuit for the inverter part. For the inverter the IC TL494 is used. The four MOSFETs IR740 are arranged in a bridge network and will be switched on two at a time alternately by the two switching MOSFETs IRF50N06 so that two will conduct at a time. The timing is set by using RC network and IC TL494 controls the waveform. The transformer will convert the output to 230 V a.c.

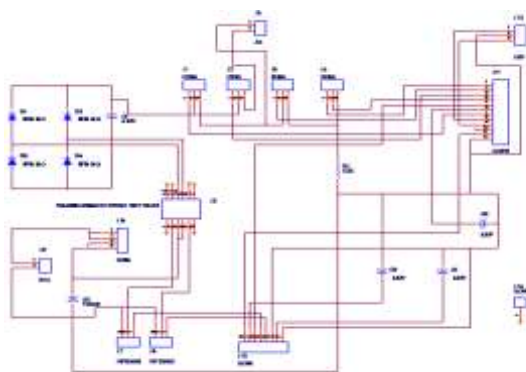


Fig.8 Schematic diagram for inverter circuit



Fig.9 Inverter circuit.

III. TESTING

The MPPT and Inverter circuit:

The circuit of the MPPT is first tested with the help of a D.C. power supply. It is checked whether the voltage is passed to the battery to charge it. Finding it to work as required, it is then tested with solar panels. The regulator is also checked by varying the d.c. voltage. It shows the expected readings on the display.



Fig.10 a. Waveform of inverter output.



b. Observation of Output on Hyper terminal.

The efficiency of the MPPT circuit is tested and found to be around 80%. It increases with the increase in intensity. The efficiency of the inverter is tested and found to be as much as 90%. It increases with increase in load.

IV. RESULTS AND ANALYSIS

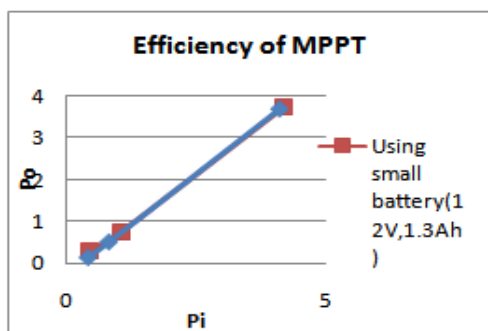


Fig 11. Efficiency of MPPT circuit

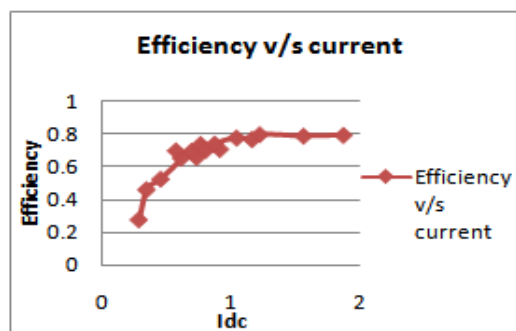


Fig12. Efficiency v/s current of inverter circuit.

The time required to charge the battery is tested. This is done first using an SMPS and then with the two solar panels. The efficiencies of the MPPT and inverter circuits are found to be around 90% and 79.9% respectively.

V. CONCLUSION

The experiments and observations shows that MPPT based charge controllers are best suitable for solar systems as they track the maximum power in case of power fluctuations at the input side due to environmental condition variation. Hence it is recommended to use the MPPT based charge controllers. Use of microcontroller

based systems provide huge computational capability and reduction in the hardware. Microcontroller is a mini computer and brings much more accuracy in the control of MOSFET and IGBT.

It is recommended to use a single phase PWM inverter with H bridge using IRF740B N-channel MOSFETs and the TL494 power supply controller. The TL494 incorporates all the functions required in the construction of a pulse-width-modulation (PWM) control circuit on a single chip. Designed primarily for power-supply control, this device offers the flexibility to tailor the power-supply control circuitry to a specific application. Several outstanding features of the developed Sinusoidal PWM inverter are: fewer harmonic, low cost, simple and compact.

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